

# Klein's model of Lobachevskii geometry

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# al-Haytham, Saccheri, Lamber

## The Euclid's V postulate

- ▶ Al-Haytham about 1000 AD considered imaginary rectangles with one non-right angle. He tried to find contradiction and by this approach to prove V Euclid's postulate.
- ▶ Saccheri, whose work was published at 1733, tried to prove V Euclid's postulate using a contradict supposition. He prove few theorem in such way and assumed that he had found the contradictions.
- ▶ Later Lambert, whose work was published at 1786, understood the case with obtuse angle is connected to spherical geometry where the largest circles on the sphere considered instead of straight-lines.

# Lobachavskii, Bolyai, Riemann

- ▶ Lobachavskii (1829) and Bolyai (1832) independently published their works concerning the non-Euclid geometry, where V postulate was changed by opposite one.
- ▶ Later at 1865 B.Riemann found unique definition on hyperbolic and spherical geometry.

# Klein' model of Lobachevskii geometry

At 1871 year Felix Klein published work where mathematical model of the Lobachevskii geometry was proposal.

Let us consider an interior of a circle  $\mathcal{U}$  such that  $x^2 + y^2 = 1$  and two points  $A(x_A, y_A)$  and  $B(x_B, y_B)$  into this circle.

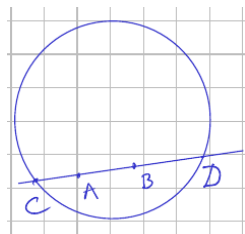
- ▶ A point in Klein's model of the Lobachevskii geometry is a point of interior of the unit circle.
- ▶ A straight line in the model is a chord of the unit circle.
- ▶ Axioms of a belonging and an order are the same as in Euclidian geometry.

# A straight line in the Klein's model

- ▶ If  $x_A \neq x_B$  and  $y_A \neq y_B$ , then these points are on the straight-line  $\mathcal{L}$  is defined as follows  $\frac{x-x_B}{x_A-x_B} = \frac{y-y_B}{y_A-y_B}$ .
- ▶ If  $x_A \neq x_B$  and  $y_A = y_B$  then the straight-line  $\mathcal{L}$  is  $y = y_1$ .
- ▶ If  $x_A = x_B$  and  $y_A \neq y_B$  then the straight-line  $\mathcal{L}$  is  $x = x_A$ .

Define  $\mathcal{L} \cap \mathcal{C} = \{C(x_C, y_C), D(x_D, y_D)\}$ . For definitely let us assume  $x_C < x_D$ ,  $x_A \neq x_B$ , and  $y_C < y_D$  in opposite case.

# A distance between two points



The distance between two different points is defined by follows rule:

$$|AB| = \left| \log \left( \frac{x_C - x_A}{x_C - x_B} : \frac{x_D - x_A}{x_D - x_B} \right) \right|, \quad x_A \neq x_B$$

$$|AB| = \left| \log \left( \frac{y_C - y_A}{y_C - y_B} : \frac{y_D - y_A}{y_D - y_B} \right) \right|, \quad y_A \neq y_B$$

here  $C(x_C, y_C)$  and  $D(x_D, y_D)$  are points on the circle  $x^2 + y^2 = 1$  and the straight-line  $(A, B)$ .

# Klein's model of Lobachevskii geometry

Consider 3 measure axioms.

- It is easy to see next equalities:

$$A \neq B \text{ then } |AB| > 0, \quad A = B \text{ then } |AB| = 0.$$

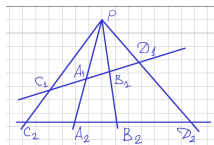
- Assume for definiteness that  $x_A < x_B$ . Let  $E$  be  $E \in [A, B]$  and  $[A, B] = [A, E] \cup [E, B]$

$$|AE| + |EB| = \log \left( \frac{x_C - x_A}{x_C - x_E} : \frac{x_D - x_A}{x_D - x_E} \right) + \log \left( \frac{x_C - x_E}{x_C - x_B} : \frac{x_D - x_E}{x_D - x_B} \right) = \log \left( \frac{x_C - x_A}{x_C - x_B} : \frac{x_D - x_A}{x_D - x_B} \right) = |AB|.$$

- The triangle inequality, which are: if  $E$  be  $E \notin [A, B]$ , then  $|A, E| + |E, B| > |A, B|$ , will be proved below.



# The cross ratio of four intervals



Let us consider two fractions. First one looks like:

$$\frac{|C_1A_1|}{|C_1B_1|} = \frac{S_{C_1A_1P}}{S_{C_1B_1P}} = \frac{|PC_1||PA_1|\sin(A_1PC_1)}{|PC_1||PB_1|\sin(B_1PC_1)} = \frac{|PA_1|\sin(A_1PC_1)}{|PB_1|\sin(B_1PC_1)},$$

and the same for another one fraction:

$$\frac{|D_1A_1|}{|D_1B_1|} = \frac{|PA_1|\sin(A_1PD_1)}{|PB_1|\sin(A_1PB_1)}.$$

So, the following cross ration depends on the angles:

$$\frac{|C_1A_1|}{|C_1B_1|} : \frac{|D_1A_1|}{|D_1B_1|} = \frac{\sin(A_1PC_1)}{\sin(B_1PC_1)} : \frac{\sin(A_1PD_1)}{\sin(A_1PB_1)}.$$

Due to the equivalence of the angles on the vertex  $P$ :

$$\frac{|C_1A_1|}{|C_1B_1|} : \frac{|D_1A_1|}{|D_1B_1|} = \frac{|C_2A_2|}{|C_2B_2|} : \frac{|D_2A_2|}{|D_2B_2|}.$$

# The triangle inequality

Due to the cross ratio:

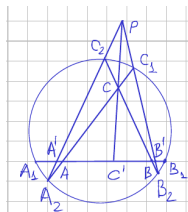
$$\frac{|A_2A|}{|A_2C|} : \frac{|AC_1|}{|CC_1|} = \frac{|A'A|}{|A'C'|} : \frac{|B'A|}{|B'C'|}$$

and

$$\frac{|B_2B|}{|B_2C|} : \frac{|C_2B|}{|C_2C|} = \frac{|A'C'|}{|A'B|} : \frac{|B'C'|}{|B'B|}.$$

Now one should prove

$$\left| \log \left( \frac{|A'A|}{|A'C'|} : \frac{|B'A|}{|B'C'|} \right) \right| + \left| \log \left( \frac{|A'C'|}{|A'B|} : \frac{|B'C'|}{|B'B|} \right) \right| > \left| \log \left( \frac{|A_1A|}{|A_1B|} : \frac{|B_1A|}{|B_1B|} \right) \right|.$$



# Transformations: rotation

Let us consider two different transformations of the circle.

- A rotation around of the origin is defined by following formulas:

$$\begin{aligned}x' &= x \cos(\alpha) - y \sin(\alpha), \\ y' &= x \sin(\alpha) + y \cos(\alpha).\end{aligned}$$

- Here we must notice that the formula for the distance independent on an angle, therefore the rotation concerns distance between two points.

# Transformations: motion

The motion is defined by following formula:

$$x' = \frac{x\sqrt{1-\beta^2}}{1+\beta y}, \quad y' = \frac{y+\beta}{1+\beta y}, \quad \beta \in (-1, 1).$$

The inverse transformation looks like:

$$x = \frac{x'\sqrt{1-\beta^2}}{1-\beta y'}, \quad y' = \frac{y-\beta}{1-\beta y'}.$$

The motion remains the sign of coordinate  $x$ , but change the scale and move the point  $A(x, y)$  up or down with respect of the sing of parameter  $\beta$ .

# Transformations: properties of the motion

- The motion remains all points in the circle. Indeed:

$$x'^2 + y'^2 - 1 = \frac{(1 - \beta^2)(x^2 + y^2 - 1)}{(1 + \beta y)^2}.$$

This expression is equal to zero if  $x^2 + y^2 = 1$  and less than zero if  $x^2 + y^2 < 1$ .

- The motion maps a straight line  $Ax + By = C$  on straight line  $A'x' + B'y' = C'$ .

# Transformation: properties of the motion

- **The motion remains an order of points on a straight line.** To prove this let us consider a points on straight line  $y = kx + c$  where  $|c| < 1$ . Then:

$$\frac{dx'}{dx} = \frac{d}{dx} \frac{x\sqrt{1-\beta^2}}{(1+\beta(kx+c))} = \frac{(c\beta+1)\sqrt{1-\beta^2}}{(kx\beta+c\beta+1)^2} > 0.$$

So the order does not change for the coordinate  $x$ . The same we can show for the transformation on the  $y$  coordinate:

$$\frac{dy'}{dy} = \frac{1-\beta^2}{(1+\beta y)^2} > 0.$$

# Transformation: properties of the motion

- **The motion remains the distance between every two points.** To prove this one should use the formula for  $x'$  where  $y$  and  $x$  are defined by the straight line  $(A, B)$ , like  $y = kx + c$ , and formula for the distance.

# Angular measure

Let us postulate the angular measure of every angle  $ABC$  with a vertex  $B$  are the same for the the angular measure of an central angle.  $A'OC'$  which are obtained by rotation and motion of the angle  $ABC$ .



# The triangle $A(0, 1/2), B(-1/2, 0), O(0, 0)$

The angular value  $AOB = \pi/2$ . To find the angular value of  $OAB$  one should move the point  $A(0, 1/2)$  into  $(0, 0)$  using the motion:

$$y' = \frac{y - 1/2}{1 - y/2}, \quad x' = \frac{x\sqrt{1 - 1/4}}{1 - y/2}.$$

So,  $A'(0, 0), B'(-\sqrt{3}/4, -1/2), O'(0, -1/2)$ . Then the angular value of  $O'A'B'$ :

$$\arctan\left(\frac{\sqrt{3}}{2}\right) < \pi/4.$$

The angular value for  $O'B'A'$  is equal to angular value of  $O'A'B'$ . As result we get the sum of angular values of vertexes for the triangle  $A, B, O$  is less than  $\pi$ .

# Bibliography

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