

Elements of approximation theory

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Taylor formula with Lagrange residue term

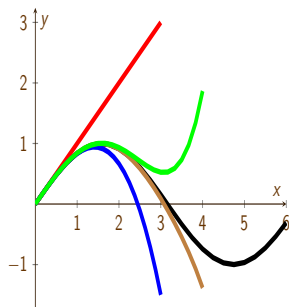
Lagrange interpolating formula

Disclaimers

Numeric value of a derivative

Numeric integration

Taylor's formula



Main idea of the Taylor formula is an approximation of given curve by polynomials of different orders. Here one can see the $\sin(x)$ (in black) and the approximation by polynomials of first (red), 3-th (blue), 5-th order (green) and 7-th orders.

Taylor's formula

Let $f(x)$ be a function which has n derivatives at $x = x_0$.

$$f(x) = f(x_0) + f'(\xi)(x - x_0) + k_2(x - x_0)^2 + k_3(x - x_0)^3 + \cdots + k_n(x - x_0)^n + o((x - x_0)^n).$$

$$f''(x) = 2k_2 + 3 \cdot 2 \cdot k_3(x - x_0) + \cdots + o((x - x_0)^{n-2}),$$

$$k_2 = \frac{f''(x_0)}{2},$$

$$f'''(x) = 3 \cdot 2 \cdot 1 \cdot k_3 + \cdots + o((x - x_0)^{n-3}),$$

$$k_3 = \frac{f'''(x_0)}{3 \cdot 2},$$

$\vdots,$

$$k_n = \frac{f^{(n)}(x_0)}{n!}.$$

Taylor's formula. Peano form of the remainder.

Theorem.

Let $f(x)$ has derivatives of n -th order at $x = x_0$, then:

$$f(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{f''(x_0)}{2!}(x - x_0)^2 + \frac{f'''(x_0)}{3!}(x - x_0)^3 + \cdots + \frac{f^{(n)}(x_0)}{n!}(x - x_0)^n + o((x - x_0)^n).$$

Taylor's formula. Lagrange form of the remainder.

$$f(x) = f(x_0) + \sum_{k=1}^{n-1} \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k + \frac{f^{(n)}(\xi)}{n!} (x - x_0)^n,$$

$$\xi \in (x_0, x).$$

Derivation of the reminder formula

Let's consider

$$\phi(\xi) = f(x) - \sum_{k=0}^{n-1} \frac{f^{(k)}(\xi)}{k!} (x - \xi)^k.$$

Then

$$\phi(x) = 0, \quad \phi(x_0) = R_n(x),$$

where $R_n(x)$ is a remainder term.

Define the difference:

$$\phi(x) - \phi(x_0) = \phi'(\xi), \quad \xi \in [x, x_0].$$

$$\phi'(\xi) = - \sum_{k=0}^{n-1} \frac{f^{(k+1)}(\xi)}{k!} (x - \xi)^k + \sum_{k=0}^{n-1} \frac{f^{(k)}(\xi)}{(k-1)!} (x - \xi)^{k-1}$$

Derivation of the reminder formula

$$\begin{aligned}\phi'(\xi) &= - \sum_{k=0}^{n-1} \frac{f^{(k+1)}(\xi)}{k!} (x - \xi)^k + \sum_{k=1}^{n-1} \frac{f^{(k)}(\xi)}{(k-1)!} (x - \xi)^{k-1} = \\ &\sum_{k=1}^{n-1} \left(\frac{f^{(k)}(\xi)}{(k-1)!} - \frac{f^{(k)}(\xi)}{(k-1)!} \right) (x - \xi)^{k-1} - \frac{f^{(n)}(\xi)}{(n-1)!} (x - \xi)^{n-1}.\end{aligned}$$

As a result one obtains:

$$\phi(x) - \phi(x_0) = \phi'(\xi)(x - x_0), \quad \phi'(\xi) = - \frac{f^{(n)}(\xi)}{(n-1)!} (x - \xi)^{n-1}.$$

Derivation of the reminder formula

To obtain the remainder in the Lagrange form use the Cauchy theorem:

$$\frac{\phi(x) - \phi(x_0)}{\psi(x) - \psi(x_0)} = \frac{\phi'(\xi)}{\psi'(\xi)},$$

$$\phi(x) - \phi(x_0) = -\frac{\psi(x) - \psi(x_0)}{\psi'(\xi)} \frac{f^{(n)}(\xi)}{(n-1)!} (x - \xi)^{n-1}.$$

The Lagrange form of the remainder:

$$-\frac{f^{(n)}(\xi)}{n!} (x - x_0)^n = -\frac{\psi(x) - \psi(x_0)}{\psi'(\xi)} \frac{f^{(n)}(\xi)}{(n-1)!} (x - \xi)^{n-1},$$

$$\psi'(\xi) = n(x - \xi)^{n-1}, \quad \psi(x) = (x - \xi)^n.$$

The remainder in the Lagrange form

$$f(x) = f(x_0) + \sum_{k=1}^{n-1} \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k + \frac{f^{(n)}(\xi)}{n!} (x - x_0)^n.$$

The Taylor formula. Examples

$$\log(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{6}{(\xi+1)^4} \frac{x^4}{4!}, \quad \xi \in (0, x);$$

$$\sqrt{1+x} = 1 + \frac{x}{2} - \frac{x^2}{8} + \frac{x^3}{16} - \frac{15}{16\sqrt{(1+\xi)^7}} x^4, \quad \xi \in (0, x).$$

Examples of interpolating polynomials

Suppose we know two points of some function:

$$\{(x_0, y_0), (x_1, y_1)\}, \quad P_1(x) = \frac{x - x_1}{x_0 - x_1} y_0 + \frac{x - x_0}{x_1 - x_0} y_1.$$

For three pair of the values we can construct unique polynomial of the second order:

$$P_2(x) = \frac{\{(x_k, y_k)\}_{k=0}^2}{(x_0 - x_1)(x_0 - x_2)} y_0 + \frac{(x - x_0)(x - x_2)}{(x_1 - x_0)(x_1 - x_2)} y_1 + \frac{(x - x_0)(x - x_1)}{(x_2 - x_0)(x_2 - x_1)} y_2.$$

Lagrange interpolation formula

Suppose we know a set of points of some function:

$$\{(x_k, y_k)\}_{k=0}^n.$$

Let $l(x) = \prod_{k=0}^n (x - x_k)$. This function is convenient to use for the definition an polynomial which passes through all of these points:

$$P_n(x) = \sum_{k=0}^n \frac{l(x)}{(x - x_k)l_k} y_k, \quad l_k = \prod_{j=0, j \neq k}^n (x_k - x_j).$$

$P_n(x)$ is called the Lagrange interpolating polynomial.

Interpolation error

Define as $x \neq x_k$:

$$\phi(\xi) = f(\xi) - P_n(\xi) - \lambda l(\xi), \quad \lambda = \frac{f(x) - P_n(x)}{l(x)}.$$

Hence $\phi(x) = 0$ and $\phi(x_k) = 0, \forall k = 0, \dots, n$. Due to the Rolle's theorem $\phi'(\zeta) = 0, \zeta \in (x_j, x_{j+1})$ and the same for $\phi^{(m)}(\zeta), m \leq n+1$:

$$\phi^{(n+1)}(\zeta) = 0, \zeta \in (a, b)$$

and

$$\phi^{(n+1)}(\xi) = f^{(n+1)}(\xi) + \lambda(n+1)!, \Rightarrow \lambda = \frac{f^{(n+1)}(\xi)}{(n+1)!}.$$

Then

$$f(x) = P_n(x) + \frac{f^{(n+1)}(\xi)}{(n+1)!} l(x).$$

Examples of interpolating polynomials

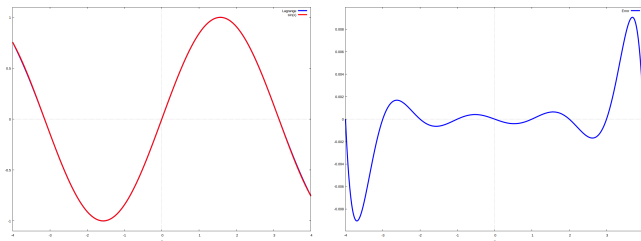


Figure: The Lagrange interpolating polynomial for the $\sin(x)$ at the points $-4, -3, -2, -1, 0, 1, 2, 3, 4$. and the error of the difference between the interpolating polynomial and $\sin(x)$.

Examples of interpolating polynomials

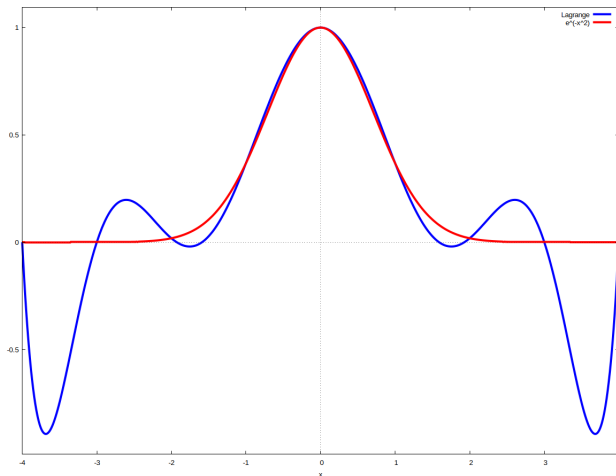


Figure: The Lagrange interpolating polynomial for the e^{-x^2} at the points $-4, -3, -2, -1, 0, 1, 2, 3, 4$.

First definition of the derivative

A derivative is a limit:

$$\frac{dy}{dx} = \lim_{\Delta x \rightarrow 0} \frac{y(x + \Delta x) - y(x)}{\Delta x}.$$

$\forall \varepsilon > 0, \exists \delta(\varepsilon) > 0, |\Delta x| < \delta:$

$$\left| \frac{y(x + \Delta x) - y(x)}{\Delta x} - \frac{dy}{dx} \right| < \varepsilon.$$

This definition appeals to properties of the curve for a **continuous parameter** Δx . While a numeric approach assumes a discrete set of allowed values of Δx .

Second definition of the derivative

$$\frac{dy}{dx} = \lim_{n \rightarrow \infty} \frac{y(x + \Delta x_n) - y(x)}{\Delta x_n}.$$

$\forall \varepsilon > 0$ and any $\{\Delta x_n\}_{n=1}^{\infty} \rightarrow 0$, $\exists N(\varepsilon)$ and:

$$\left| \frac{y(x + \Delta x_n) - y(x)}{\Delta x_n} - \frac{dy}{dx} \right| < \varepsilon.$$

This concept looks close to the numeric approach but basic details are the words **any** and **convergent** sequence.

Disclaimer

When we deal with numeric formulas for the derivative then we must understand that we neglect two important ideas of the classical mathematical analysis:

- ▶ continuous function;
- ▶ continuous of independent variable.

We change the continuous by the a set of values of the floating point numbers.

Disclaimer

Despite of following exaples we will assume that the numbers are a set on a **lattice with uniform step Δ** ..

► Noncommutativity:

```
> > >2.0-0.3+0.3==2.0
```

```
true
```

```
> > >2.0+0.3-0.3==2.0
```

```
false
```

► An errors due to averaging by standard IEEE754

```
> > >z=2.0-0.9
```

```
> > >"%.18f" % z
```

```
'1.1000000000000000089'
```

Approximations of derivatives

Let's consider a Taylor formula for a smooth function $f(x)$ with a residue in the Lagrange form:

$$f(x + \Delta) = f(x) + f'(x)\Delta + O(\Delta^2).$$

It yields:

$$f'(x) = \frac{f(x + \Delta) - f(x)}{\Delta} + O(\Delta).$$

Two-point formula for the derivative

If we consider three terms of the Taylor series:

$$f(x + \Delta) = f(x) + f'(x)\Delta + \frac{f''(x)}{2!}\Delta^2 + O(\Delta^3).$$

Here second derivative is:

$$f''(x) = \frac{1}{\Delta} \left(\frac{f(x + \Delta) - f(x)}{\Delta} - \frac{f(x) - f(x - \Delta)}{\Delta} \right) + O(\Delta) = \frac{f(x + \Delta) - 2f(x) + f(x - \Delta)}{\Delta^2} + O(\Delta).$$

In this case:

$$f(x + \Delta) = f(x) + f'(x)\Delta + \frac{f(x + \Delta) - 2f(x) + f(x - \Delta)}{2!} + O(\Delta^3)$$

and

$$f'(x) = \frac{f(x + \Delta) - f(x - \Delta)}{2\Delta} + O(\Delta^2).$$

Two two-point formulas for the derivative

$$f'(x) = \frac{f(x + \Delta) - f(x)}{\Delta} + O(\Delta),$$

$$f'(x) = \frac{f(x + \Delta) - f(x - \Delta)}{2\Delta} + O(\Delta^2).$$

Four-point formulas for the derivative

The four terms of the Taylor series:

$$f(x + \Delta) \sim f(x) + f'(x)\Delta + \frac{f''(x)}{2!}\Delta^2 + \frac{f'''(x)}{3!}\Delta^3.$$

Here

$$f'''(x) = \frac{f''(x + \Delta) - f''(x - \Delta)}{2\Delta} + O(\Delta^2).$$

$$\begin{aligned} f'''(x) &= \frac{1}{2\Delta^3} (f(x + 2\Delta) - 2f(x + \Delta) + f(x)) - \\ &\quad - \frac{1}{2\Delta^3} (f(x) - 2f(x - \Delta) + f(x - 2\Delta)) \end{aligned}$$

Then:

$$f'(x) = \frac{1}{12\Delta} (f(x+2\Delta) - 8f(x+\Delta) + 8f(x-\Delta) - f(x-2\Delta)) + O(\Delta^4).$$

Formulas for first derivative

$$f'(x) = \frac{f(x + \Delta) - f(x)}{\Delta} + O(\Delta),$$

$$f'(x) = \frac{f(x + \Delta) - f(x - \Delta)}{2\Delta} + O(\Delta^2),$$

$$f'(x) = \frac{1}{12\Delta}(f(x + 2\Delta) - 8f(x + \Delta) + 8f(x - \Delta) - f(x - 2\Delta)) + O(\Delta^4).$$

Examples

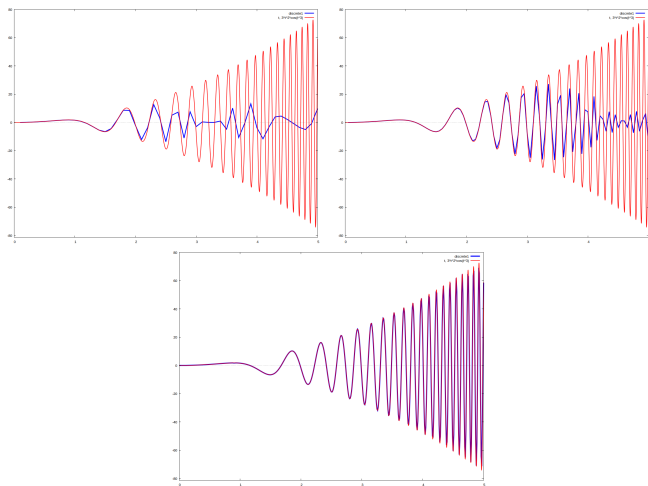


Figure: The numeric derivative of $\sin(x^3)$ on the interval $x \in [0, 5]$ with steps 0.1, 0.05, 0.01.

General formula for the numeric integration

$$\int_a^b f(x) dx = \sum_{k=0}^N c_k f(x_k) + R.$$

Here

- ▶ x_k is a knot of the lattice;
- ▶ N is the number of the number of the knots in the interval $[a, b]$;
- ▶ c_k is a weight coefficient;
- ▶ R is the residue term, which is difference between the approximation sum and the value of the integral.

The simplest case

Let's consider an uniform lattice of N knots on the interval and $x_{k+1} - x_k = (b - a)/N = \Delta$.

$$f(x) = f(x_k) + O(\Delta), \quad x \in [x_k, x_{k+1}),$$

so

$$\int_a^b f(x) dx = \sum_{k=0}^N f(x_k) \Delta + O(\Delta).$$

Trapezoidal approximation

$$f(x) = f(x_k) + \frac{f(x_{k+1}) - f(x_k)}{\Delta}x + O(\Delta^2), \quad x \in [x_k, x_{k+1}],$$

Then integral over the interval $x \in [x_k, x_{k+1}]$:

$$\begin{aligned} \int_{x_k}^{x_{k+1}} \left(f(x_k) + \frac{f(x_{k+1}) - f(x_k)}{\Delta}x \right) dx &= \\ f(x_k)\Delta + \frac{1}{2\Delta}f(x_{k+1})\Delta^2 - \frac{1}{2\Delta}f(x_k)\Delta^2 &= \\ \frac{1}{2}(f(x_{k+1}) + f(x_k))\Delta. \end{aligned}$$

Trapezoidal approximation

$$\int_a^b f(x) dx = \sum_{k=0}^{N-1} \int_{x_k}^{x_{k+1}} \left(f(x_k) + \frac{f(x_k) - f(x_{k+1})}{\Delta} x \right) dx +$$

$$O(\Delta^2) = \sum_{k=0}^{N-1} \frac{1}{2} (f(x_{k+1}) + f(x_k)) \Delta + O(\Delta^2)$$

As a result:

$$\int_a^b f(x) dx = \frac{1}{2} f(x_0) \Delta + \sum_{k=1}^{N-1} f(x_k) \Delta + \frac{1}{2} f(x_N) \Delta + O(\Delta^2).$$

Formulas for integration over finite interval

$$\int_a^b f(x) dx = \sum_{k=0}^N f(x_k) \Delta + O(\Delta).$$

$$\int_a^b f(x) dx = \frac{1}{2} f(x_0) \Delta + \sum_{k=1}^{N-1} f(x_k) \Delta + \frac{1}{2} f(x_N) \Delta + O(\Delta^2).$$

A high order approximation one can obtain if one chose a formula for high level of approximation of the curve on the elementary interval.

An example

$$\int_0^{2\pi} \sin(x^3) dx \sim 0.4548524546$$

The same integral calculated by the trapezoid method with step 0.0001 :

0.45483

Summary

Taylor formula with Lagrange residue term

Lagrange interpolating formula

Disclaimers

Numeric value of a derivative

Numeric integration